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Thesis Committee, Dr. Ross Snider And Mr. Randy Larimer, As Well As Dr. Todd Kaiser, Who With Dr. Snider Was A Supervising Faculty Member On The Project. I Also Want To Thank Leigh Smith With NASA's Marshall Space Flight Center And Robert Ray Jr. For Their Supervision And Advice Throughout The Project. Fellow Students Jylissa Whisenhunt, Feb 3th, 2024

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Fault-Tolerant Adaptive Model Predictive Control Using ...

Chapter 4 Model Predictive Control Literature Review 98 4.1. Literature Review About Adaptive Model Predictive Control 98 4.2. Literature Review Of Fault-Tolerant Model Predictive Control 102 4.3. Summary 104 Chapter 5 Fault-Tolerant Adaptive Model Predictive Control For Flight Systems 105 5.1. Flight Control Systems 105 Apr 4th, 2024

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Diverse Control Techniques For The Most Part Intended For UAVs Are Feedback Linearization [2], [3], Backstepping Control [4], And Siding Mode Control (SMC) [5], [6]. Manuscript Received November 22, 2018; Revised July 22, 2019. Some Different Techniques Are Implemented On A Linearized Model Of Quadrotor And A Comparison Of The Feb 10th, 2024

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Can Be Done Through An API Invocation, Scriptable Command-line Tools, Or The AWS Management Console. Additionally, An Auto Scaling Group Can Be Configured To Automatically Replace Failed Or Degraded Instances. The Ability To Quickly Replace A Problematic Instance Is Just The First Step Toward Jan 4th, 2024

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