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Required System Dynamics, Which In Turn Allows Us To Establish Regions Of Stability. To Summarize, The Main Contributions Of This Work Are As Follows: We Formulate The Searching Of Safe Regions For Arbitrary Nonlinear Dynamical Systems As A Convex Optimization Problem, By Dealing With A Scalar Function Of States. Apr 5th, 2024

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Quadratic Lyapunov Functions For Odd Polynomial Systems. Int. J. Robust Nonlinear Control, 15:35-49, 2005. [10] H.-D. Chiang And J. S. Thorp. Stability Regions Of Nonlinear Dynamical Systems: A Constructive Methodology. IEEE Transaction On Automatic Control, 34(12):1229-1241, 1989. 1 Feb 6th, 2024

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