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The Feedback Wire (white) For Each Servo Will Be Attached To The Arduino Pins As Follows: Servo One - PWM -> Digital 8, Feedback -> Analog 1 Servo Two - PWM -> Digital 9, Feedback -> Analog 2 Servo Three - PWM -> Digital 10, Feedback -> Analog 3 Servo Four - PWM -> Digital 11, Mar 13th, 2024

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Required Control Signal To The Servo Motors. 2.3 Servo Motors In This Design, DC Servo Motors Were Used To Achieve The Different Movements Of The Robotic Arm. DC Servo Motors Are DC Motors Possessing An Internal Feedback Mechanism For Achieving Controlled Rotations. The DC Servo Motor Mar 2th, 2024

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Gripper Rotation Gear Can Rotate The Whole Gripper. This Gripper Rotation Gear Is Fixed To The Gripper Base. Fig 15: Gripper Rotation Gear . 4.16 Gear Case: Gear Case Consist Of All Gears That Is Motion Changing Gears And The Motor Is Fixed To This Gear Case. Fig 16: Gear Case . 4.17 Gripper Worm Gear: Gripper Apr 11th, 2024.

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