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Contribution Leading To New Control Theory. Several Other Methods Of Robust Control, Such As Sliding Modes And Lyapunov Methods, Have Also Been Applied To The Robust Control Problem For Robot Manipulators. The Mid-1980s Were Also A Time Of Development In Adaptive Control, And Again The Connection With Robotics Was Pursued. Mar 15th, 2024

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T. C. Henderson School Of Computing University Of Utah 50 S. Central Campus Drive, Room 3190 Salt Lake City, UT 84112 Keywords: Evolutionary Robotics, Robot Colonies, Mobile Robots, Evolutionary Neural Computing, Behavioral Robotics, Vision, Robot Vision Abstract--This Paper Describes The Development And Feb 23th, 2024

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