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The Regulation Is Achieved By A PID Controller. Simulink Model Of The Closed Loop Converter Is Shown In Figure 7b. Simulink PID Control Block Is Illustrated In Figure 7c . The Parameters Used For The Closed-loop Simulation Are : Vi = 12 V L = 300 H C Jan 5th, 2024

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3 Agenda –Day 2 Day 2 10:00 Am -11:00 Pm •Mechanical Engineering And Control System Concepts Using MATLAB And Simulink. Mechanical Enginee Jan 2th, 2024

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