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The Hardware For The Four Quadrant Dc Motor Speed Control Using Arduino Is
Designed. It Is Proved To Be Operated So Simple. In The Proposed Model, We Have
Used Arduino Which Generates PWM Signal. The PWM Technique Has Been Used To
Control The Speed Of Dc Motor. By Variation In Duty Cycle, FOUR QUADRANT DC
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C. Pulse Width Modulation Technique A). Sinusoidal Pulse Width Modulation
Technique Multiple Numbers Of Output Pulse Per Half Cycle And Pulses Are Of

Different Width. The Width Of Each Pulse Is Varying Jan 14th, 2024

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A. Motor Equations . The Electric Equivalent Circuit Of The Armature And The Free-body Diagram Of The Rotor Are Shown In The Figure 2, Where . R. A. And . L. A. Are The Equivalent Resistance And Inductance, Respectively, Of The Armature Winding, I. A. The Armature Current, V. The Input . Evoltage, A. The Induback Electroced -motive Mar 8th, 2024

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Driver Fault Signal, Which Indicates That At Least One Fault Event Has Occurred. The Phase Voltage Signals Enter The LPFs. Their Cutoff Frequency Is Three Times Higher Than The Phase Switching Frequency Generated By The Motor Driver. The PSoC Analog Blocks Process The Phase Voltages. As Mentioned Above, PSoC's AGND Is Floating And Apr 7th, 2024

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